

Mathematician spotlight: Henry Segerman, Assistant Professor, Oklahoma State University

- Studies 3-manifolds, triangulations, hyperbolic geometry
- does mathematical visualization, 3D printing, virtual reality for visualization
- creates 3D printed objects that blend math and art (IMHO)

Last time: We discovered how to describe a surface parametrically, with two parameters: $\vec{x}(s,t)$
 We determined that the normal vector to the surface is $\vec{n} = \vec{x}_s \times \vec{x}_t$ (etc.)

Today: We are integrating **Scalar functions over Curves** and **vector functions over Surfaces**: Scalar surface integrals!

First, let's find a tangent plane.

Example: Find an equation for the tangent plane to DD's favorite surface,

$$\vec{x}(r, \theta) = [r \cdot \cos \theta, r \cdot \sin \theta, \cos r], \text{ for } 0 \leq r \leq \infty, \text{ at } (1, 0, \cos 1), \text{ i.e. when } r=1, \theta=0.$$

r-curves: $\theta=0 \Rightarrow \vec{x}(r, 0) = [r, 0, \cos r]$ } cosine curves
 • hold θ constant $\theta = \frac{\pi}{2} \Rightarrow \vec{x}(r, \frac{\pi}{2}) = [0, r, \cos r]$ } radiating
 • vary r } out from 0

θ -curves: $r=1 \Rightarrow \vec{x}(1, \theta) = [\cos \theta, \sin \theta, \cos 1]$ } circles at
 • hold r constant $r=10 \Rightarrow \vec{x}(10, \theta) = [10 \cos \theta, 10 \sin \theta, \cos 10]$ } undulating
 • vary θ } heights



looks like circular waves propagating out in the water

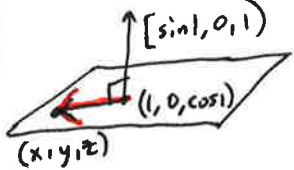
$$\vec{x}_r = [\cos \theta, \sin \theta, -\sin r] \Rightarrow \vec{x}_r(1, 0) = [1, 0, -\sin 1]$$

$$\vec{x}_\theta = [-r \sin \theta, r \cos \theta, 0] \Rightarrow \vec{x}_\theta(1, 0) = [0, 1, 0]$$

$$\Rightarrow \vec{x}_r \times \vec{x}_\theta = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & -\sin 1 \\ 0 & 1 & 0 \end{vmatrix} = [\sin 1, 0, 1] = \vec{n}$$

normal vector to surface at $(1, 0, \cos 1)$

Recall: The plane passing through $(1, 0, \cos 1)$ with normal vector $[\sin 1, 0, 1]$



is the collection of points (x, y, z) such that

$$\begin{bmatrix} \sin 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x-1 \\ y-0 \\ z-\cos 1 \end{bmatrix} = 0 \Rightarrow \sin 1(x-1) + 0(y-0) + 1(z-\cos 1) = 0$$

$$\Rightarrow x \cdot \sin 1 - \sin 1 + z - \cos 1 = 0 \Rightarrow \underline{\underline{x \cdot \sin 1 + z = \cos 1 - \sin 1}}$$

tangent plane equation.

What a cool surface! How would we ever calculate its surface area, for instance?

Surface area: Consider a surface S parameterized by $\vec{x}(s,t)$, defined over a region D of the st -plane.

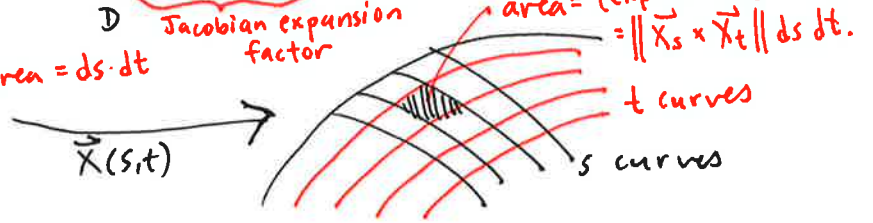
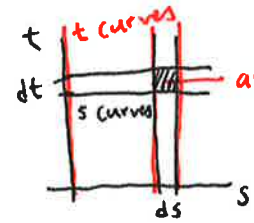
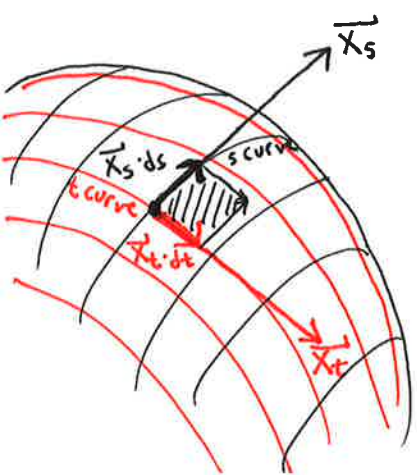
Last time, we showed that \vec{x}_s and \vec{x}_t are tangent to the surface in different directions.

Recall that $\|\vec{u} \times \vec{v}\|$ is the area of the parallelogram spanned by vectors \vec{u} and \vec{v} ,
 so $\|\vec{x}_s \times \vec{x}_t\|$ " " " " " " " " \vec{x}_s and \vec{x}_t .

Idea: Make a tiny vector in the s -direction: $\vec{x}_s \cdot ds$ ← tiny distance
 and " " " " t -direction: $\vec{x}_t \cdot dt$ ←

Then $\|\vec{x}_s ds \times \vec{x}_t dt\| = \text{area of tiny parallelogram} = \|\vec{x}_s \times \vec{x}_t\| ds dt$
 pull out constants

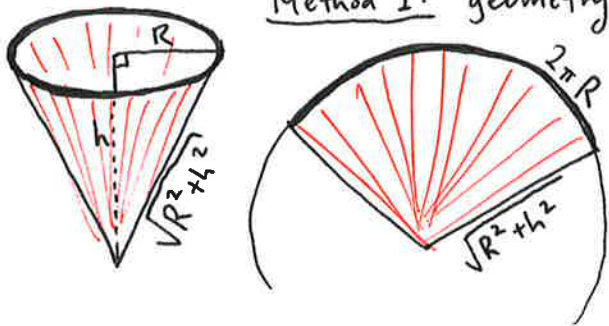
So Surface area of $S = \iint_D \|\vec{x}_s \times \vec{x}_t\| ds dt$.
 Jacobian expansion factor



area = (exp. factor) $ds dt$
 $= \|\vec{x}_s \times \vec{x}_t\| ds dt$

Example. Find the surface area of a cone of radius R and height h .

Method 1: geometry. Cut open the cone and lay it flat.



$$\begin{aligned} \text{area} &= \left(\frac{\text{area of disk of radius } \sqrt{R^2+h^2}}{\sqrt{R^2+h^2}} \right) \times \left(\text{proportion of the disk that we have} \right) \\ &= \pi \left(\sqrt{R^2+h^2} \right)^2 \times \left(\frac{2\pi R}{2\pi \sqrt{R^2+h^2}} \right) \\ &= \pi R \sqrt{R^2+h^2}. \end{aligned}$$

Method 2: Parameterize the surface and integrate $\iint_D \|\vec{x}_r \times \vec{x}_\theta\| dr d\theta$.

$$\vec{x}(r, \theta) = [r \cdot \cos\theta, r \cdot \sin\theta, \frac{h}{R} \cdot r]$$

$$\vec{x}_r = [\cos\theta, \sin\theta, \frac{h}{R}] \Rightarrow \vec{x}_r \times \vec{x}_\theta = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos\theta & \sin\theta & h/R \\ -r\sin\theta & r\cos\theta & 0 \end{vmatrix} = [-\frac{h}{R} \cdot r \cos\theta, -\frac{h}{R} \cdot r \sin\theta, r]$$

$$\vec{x}_\theta = [-r\sin\theta, r\cos\theta, 0] \Rightarrow \|\vec{x}_r \times \vec{x}_\theta\| = r \frac{\sqrt{R^2+h^2}}{R}$$

$$\text{So surface area} = \int_{\theta=0}^{2\pi} \int_{r=0}^R r \frac{\sqrt{R^2+h^2}}{R} dr d\theta = \frac{\sqrt{R^2+h^2}}{R} \int_{\theta=0}^{2\pi} d\theta \cdot \int_{r=0}^R r dr = \frac{\sqrt{R^2+h^2}}{R} \cdot 2\pi \cdot \frac{R^2}{2} = \pi R \sqrt{R^2+h^2} \quad \text{☺}$$

Scalar surface integrals! Integrating a scalar function over a surface.

$$\text{Surface area} = \iint_D 1 dS = \iint_D \underbrace{1}_{\downarrow dS} \|\vec{x}_s \times \vec{x}_t\| ds dt$$

dS = tiny piece of area on our surface S

we can replace 1 with a function that assigns a value (temperature, density, charge) to each point, and integrate it.

Scalar surface integral of $f(x,y,z)$ over $S = \vec{x}(s,t)$ on D

$$= \iint_D f(x,y,z) dS = \iint_D f(\vec{x}(s,t)) \underbrace{\|\vec{x}_s \times \vec{x}_t\|}_{\downarrow dS} ds dt$$

Example. Compute $\iint_S xy dS$, where S is the unit disk in the xy -plane.

Method 1: set it up in polar coords:

$$\iint_S xy dA = \int_{\theta=0}^{2\pi} \int_{r=0}^1 \underbrace{(r \cdot \cos\theta)}_x \underbrace{(r \cdot \sin\theta)}_y \cdot \underbrace{r \cdot dr \cdot d\theta}_{dA} = \dots$$

Here, the "surface" we are integrating over is a part of our familiar xy -plane.

Method 2: set it up as a surface integral:

$$\vec{x}(r, \theta) = [r \cdot \cos\theta, r \cdot \sin\theta, 0] \text{ for } \begin{cases} 0 \leq \theta \leq 2\pi \\ 0 \leq r \leq 1 \end{cases} D$$

$$\vec{x}_r = [\cos\theta, \sin\theta, 0] \Rightarrow \vec{x}_r \times \vec{x}_\theta = [0, 0, r] \Rightarrow \|\vec{x}_r \times \vec{x}_\theta\| = r$$

$$\text{so } \iint_S xy \cdot dS = \iint_D f(r \cdot \cos\theta, r \cdot \sin\theta, 0) \|\vec{x}_r \times \vec{x}_\theta\| dr d\theta = \int_{\theta=0}^{2\pi} \int_{r=0}^1 \underbrace{(r \cos\theta)(r \sin\theta)}_{f(x,y,z)=xy} \cdot \underbrace{r}_{\|\vec{x}_r \times \vec{x}_\theta\|} dr d\theta$$